

# Math 1b Midterm 1 Review

## § 9.1 Modeling with Differential equations

Examples: Population  $\rightarrow P'(t) = kP(t)$

Spring  $\rightarrow$  Hooke's law. force  $= -kx = m \frac{d^2x}{dt^2}$

Definition: order of a differential equation is the maximum derivative taken

Definition:  $f$  is a solution if  $y = f(x)$  satisfies the differential equation  
(note - it used to be that functions HAD solutions, but with DiffEQ's, they ARE solutions)

Definition: the initial condition is the point you know on the curve so that you can get rid of the constant.

Look at problems 3, 7, 11.

## § 9.2 Direction Fields and Euler's Method

Definition: A solution curve is a graph of points  $(x, y)$  satisfying the DiffEQ through a particular point. Given a DiffEQ, we don't necessarily know the original function, but in many cases we know a lot about the slope. For example, if it's a first order DiffEQ, we can plug in points  $(x, y)$  to compute  $y'$  at different spots in the plane. Drawing these in gives a direction field or slope field.

Just as you can find an approximate solution graph with an initial value and slope field, Euler's method is a bit more precise.

Choose a step-value  $h$ .  $x_{n+1} = x_n + h$ .

$y_{n+1} = y_n + hF(x_n, y_n)$  where  $F$  is the <sup>first order</sup> DiffEQ

look at problems 13, 19, 27.