

# 1 Section 2.4

## 1.1 Problem 14

$V$  has basis

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$
$$B = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$
$$C = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

and  $F^3$  has basis  $a = (1, 0, 0)$ ,  $b = (0, 1, 0)$ ,  $c = (0, 0, 1)$ . A linear transformation is uniquely defined by how it acts on a basis, so define a linear transformation  $T : V \rightarrow F^3$  by  $T(A) = a$ ,  $T(B) = b$ ,  $T(C) = c$  and extending this linearly on linear combinations  $\alpha A + \beta B + \gamma C$  for  $\alpha, \beta, \gamma \in F$ . This is clearly onto since it is onto a basis of  $F^3$  and is linear by definition. If  $T(\alpha A + \beta B + \gamma C) = 0$  we have  $\alpha a + \beta b + \gamma c = 0 \Rightarrow \alpha = \beta = \gamma = 0$  since  $\{a, b, c\}$  is a basis; so  $N(T) = 0 \Rightarrow T$  is one-to-one. So  $T$  is invertible and therefore an isomorphism.

## 1.2 Problem 16

$\Phi(aA + cC) = B^{-1}(aA + cC)B = aB^{-1}AB + cB^{-1}CB = a\Phi(A) + c\Phi(C) \Rightarrow \Phi$  is linear. Clearly by the same logic the map  $\Psi : M_{n \times n}(F) \rightarrow M_{n \times n}(F)$  defined by  $\Psi(A) = BAB^{-1}$  is linear, and  $\Phi(\Psi(A)) = BB^{-1}ABB^{-1} = A = B^{-1}BAB^{-1}B = \Psi(\Phi(A)) \Rightarrow \Phi\Psi = \Psi\Phi = \mathbf{1} \Rightarrow \Psi = \Phi^{-1}$ . Therefore  $\Psi$  is invertible.

## 1.3 Problem 17

### 1.3.1 (a)

Let  $x, y \in T(V_0)$ . Then  $\exists a, b \in V_0$  s.t.  $T(a) = x$  and  $T(b) = y$ . Since  $V_0$  is a subspace,  $z = ca + db \in V_0$  for any  $c, d \in F$  so  $T(z) = cx + dy \in T(V_0)$ . Therefore  $T(V_0)$  is a subspace of  $W$ .

### 1.3.2 (b)

Let  $\{v_1, \dots, v_k\}$  be a basis for  $V_0$ . Let  $w_i = T(v_i)$ . Then  $\{w_i\}$  spans  $T(V_0)$  by definition, and if  $\sum c_i w_i = 0$  for  $c_i \in F$  then by linearity  $T(\sum c_i v_i) = 0 \Rightarrow c_i v_i = 0$  (since  $T$  is one-to-one)  $\Rightarrow c_i = 0$  for all  $i$ . Therefore  $\{w_i\}$  is a basis for  $T(V_0)$  which shows  $\dim(V_0) = \dim T(V_0)$ .

## 2 Section 2.5

### 2.1 Problem 6

In each case the matrix  $Q$  is the change-of-basis matrix  $(Id)_E^\beta$  whose columns are the vectors of  $\beta$ . Here  $E$  denotes the standard basis. We find  $(L_A)_\beta$  by computing  $T(\beta_i)$  for all  $1 \leq i \leq \dim V$ . ( $T = L_A$ )

#### 2.1.1 (a)

$$T(\beta_1) = (4, 2)^t = 6\beta_1 - 2\beta_2 \quad T(\beta_2) = (7, 3)^t = 11\beta_1 - 4\beta_2$$

so

$$(L_A)_\beta = \begin{bmatrix} 6 & 11 \\ -2 & -4 \end{bmatrix}$$

#### 2.1.2 (b)

$$T(\beta_1) = (1, 3, 2)^t = 2\beta_1 - 2\beta_2 + 1\beta_3 \quad T(\beta_2) = (0, 3, 1)^t = 2\beta_1 - 3\beta_2 + 1\beta_3 \quad T(\beta_3) = (0, 4, 2)^t = 2\beta_1 - 4\beta_2 + 2\beta_3$$

so

$$(L_A)_\beta = \begin{bmatrix} 2 & 2 & 2 \\ -2 & -3 & -4 \\ 1 & 1 & 2 \end{bmatrix}$$

### 2.2 Problem 7

For both parts, choose the basis  $\beta = \{(1, m), (-m, 1)\}$ .

#### 2.2.1 (a)

$T(\beta_1) = \beta_1$  and  $T(\beta_2) = -\beta_2$ . So

$$(T)_\beta = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

#### 2.2.2 (b)

In this case we take  $W_1$  to be the given line  $L$  and  $W_2$  to be the line perpendicular to it. Since  $\beta_i \in W_i$  for  $i = 1, 2$  we have

$T(\beta_1) = \beta_1$  and  $T(\beta_2) = 0$ . So

$$(T)_\beta = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

### 3 Problem 8

This is evident by the definitions given in the problem:  $Q = (I)_{\beta}^{\beta}$ , and  $P = (I)_{\gamma}^{\gamma}$  implies  $P^{-1} = (I)_{\gamma}^{\gamma'}$