

(a) Since  $V^*$  is  $(n+1)$ -dimensional, to show that  $\{f_0, \dots, f_n\}$  is a basis for  $V^*$  it suffices to show that it is LI.

Suppose that

$$a_0 f_0 + \dots + a_n f_n = 0 \quad \text{---(1)} \quad \text{where } a_0, \dots, a_n \in \mathbb{F}$$

Applying (1) to the polynomial  $(x-c_0)(x-c_1)\dots(x-c_n)$  we find that

$$a_0(c_0-c_1)(c_0-c_2)\dots(c_0-c_n) + a_1 \cdot 0 + \dots + a_n \cdot 0 = 0$$

Since the scalars  $c_0, \dots, c_n$  are distinct,  $(c_0-c_1)\dots(c_0-c_n) \neq 0$  and so  $a_0$  must be zero.

Similarly, applying (1) to  $(x-c_0)(x-c_1)(x-c_3)\dots(x-c_n)$  we conclude that  $a_1 = 0$ , and so on.

Thus  $a_0 = a_1 = \dots = a_n = 0$ , and so  $\{f_0, \dots, f_n\}$  is LI.

Thus  $\{f_0, \dots, f_n\}$  is a basis for  $V^*$ .

(b) The Corollary to Theorem 2.26 implies that there is a basis  $\{p_0, \dots, p_n\}$  for  $V$  for which  $\{f_0, \dots, f_n\}$  is the dual basis. In other words,  $f_i(p_j) = \delta_{ij}$

$$\text{i.e. } p_j(c_i) = \delta_{ij}$$

$$\Rightarrow p_i(c_j) = \delta_{ij}$$

↑  
this notation means  
"1 if  $i=j$  and  
0 if  $i \neq j$ "

(c) We want to find a polynomial  $q(x) \in V$  such that  $q(c_0) = a_0, \dots, q(c_n) = a_n$ . But  $\{p_0, \dots, p_n\}$  is a basis for  $V$ , so if  $q$  exists we can write it