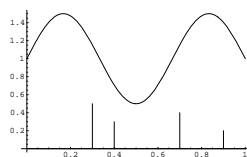


## ABSTRACT.

INVARIANT MEASURES. A bounded linear map  $\phi$  on the set  $C(X)$  of all continuous functions on  $X = [0, 1]$  is called a **measure**. It is called **positive** if  $\phi(f) \geq 0$  if  $f \geq 0$ . One writes also  $\mu(f) = \int f d\mu$ . By approximation of  $1_{a,b}$  by continuous functions  $f_n$  (for example with Fourier series), one can define  $\mu([a, b]) = \int_a^b d\mu = \int_0^1 f_n(x) d\mu(x)$  and think of  $\mu$  as a function defined on a set of subsets of the real lines. If  $\mu$  is a positive measure and  $\mu(1) = 1$  if  $1(x) = 1$  is the function which is constant **1**, then  $\mu$  is called a **probability measure**. A measure is called  **$g$ -invariant** if  $\int g(f(x)) d\mu(x) = \int f(x) d\mu(x)$ . The measure  $\mu(g) = \frac{1}{n} \sum_{k=1}^n g(x_k)$  where  $x_0, x_1, \dots, x_n$  is an  $n$ -cycle is an invariant measure. A  $T$ -invariant measure is called **ergodic**, if all invariant sets have measure zero or one.

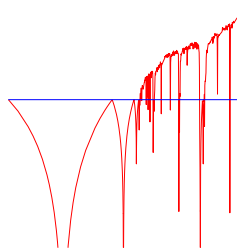


## EXAMPLES.

1) The map  $T(x) = x + \alpha \pmod{1}$  has the Lebesgue measure  $dx$  invariant. The Lebesgue measure is defined by the usual integration  $\phi(f) = \int_0^1 f(x) dx$  is a probability measure. If  $\alpha$  is irrational, then it is ergodic.  
 2) If  $T(x) = 4x(1-x)$  on  $I = [0, 1]$ , then  $dx/(\pi\sqrt{x(1-x)})$  is an invariant measure. It is known to be ergodic.  
 3) If  $T(x) = 1/x \pmod{1}$ , then  $\frac{1}{\log(2)} dx/(1+x)$  is an invariant measure for the Gauss map  $T$ . It is important in number theory because if  $x = [a_1, \dots]$  is the continued fraction expansion of  $x$ , then  $\sum_{i=0}^{n-1} f(T^i x) = \sum_{i=1}^n a_i$  if  $f(x) = [1/x]$ . Also this measure is known to be ergodic for  $T$ .  
 4) If  $T(x) = 10x \pmod{1}$ , then the Lebesgue measure  $dx$  is an invariant measure. But there are many more invariant measures: for example, the measure located on the set  $\{x_1 = 0.123123123123\dots, x_2 = 0.23123123123\dots, x_3 = 312312312312\dots\}$  which assigns weight  $1/3$  to each point is an invariant measure.

## LYAPUNOV EXPONENT OF INVARIANT MEASURE.

For an invariant measure  $\mu$  of a continuously differentiable map  $f$ , define the **Lyapunov exponent**  $h_\mu(T) = \int_0^1 \log |f'(x)| d\mu(x)$ . If  $\mu$  is supported on a periodic point, then the periodic orbit is stable if and only if the Lyapunov exponent is negative. Numerically, Lyapunov exponents can be computed by looking at the accumulation points of  $\frac{1}{n} \sum_{k=1}^n \log |f'(T^k(x))|$  for large  $n$  (usually the limit exists). The reason why this works is that the measures  $\mu_n(f) = \sum_{k=1}^n f(T^k x)$  have as accumulation points invariant measures.



PHYSICAL AND SRB MEASURES. In many situations, the limiting measure of  $\mu_n(f) = \sum_{k=1}^n f(T^k x)$  exists and is the same for almost all initial conditions. One calls such a measure a **physical measure**. In the case of a positive Lyapunov exponent and if the measure is absolutely continuous (given by a density  $\mu(f) = \int \rho(x)f(x) dx$ ), such measures are called **Sinai-Ruelle-Bowen measures** or simply **SRB-measures**. It is difficult to decide whether for a specific parameter  $c$  in the quadratic family, there is such a measure or not. One knows for example that for an open and dense set of parameters, the map has a periodic attractor with a negative Lyapunov exponent.

## EXAMPLES.

1)  $T(x) = 4x(1-x)$  has the Lyapunov exponent  $\int_0^1 \log |4-8x|/\sqrt{x(1-x)} dx = \log(2)$ .  
 2)  $T(x) = \frac{1}{x} \pmod{1}$  has the Lyapunov exponent  $\frac{1}{\log(2)} \int_0^1 -2 \log(x)/(1+x) dx$ .  
 3)  $T(x) = 7x \pmod{1}$  with the invariant measure  $dx$  and the Lyapunov exponent  $\log(7)$ .